

RT: Real-time Position Tracking System

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Abstract

- ◆ Heel-attached module to track operators in a Clean Room.
- ◆ Operators' locations are to be displayed on LabVIEW® screen.

Introduction

- A module containing MEMS inertia sensors, RFID reader, RF module, CPU, Battery, & contactless charging unit tracks operators.
- Inertia sensors send data for estimating position, and RFID calibrates its error.
- 9 operators can be tracked simultaneously.

Methods

- 3 axis accelerometer and 3 axis gyroscope are embedded along with a RFID reader.
- Sensors are monitored every 10ms, data are transmitted every 100ms to the server.
- Around 20 parameters are to be used in calculations for one module.

Results



Fig. 1. PCB



Fig. 2. Monitor Screen

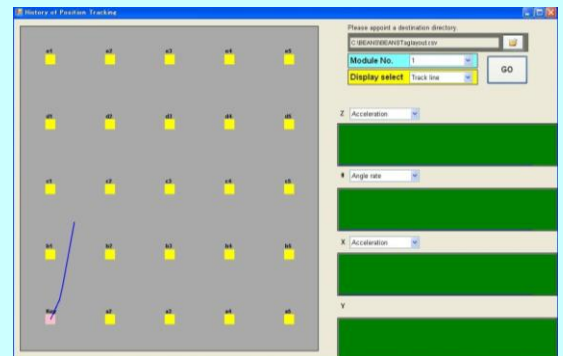


Fig. 3. Trace Display

Summary

- ① Sensor data were successfully captured by the server.
- ② Position tracking algorithm is tested right now.
- ③ Automatic tuning can be added in 2011.